|  |
| --- |
| What did it feel like to touch the ground without seeing it? |
|  |
| Suggest some reasons why robots would benefit from a ground sensor. |
|  |
| To what value do we need to compare the ground sensor block? |
|  |
| What blocks can we use to include both foot sensors in the program? |
|  |
|  |

# 

|  |
| --- |
| **Record your plan for the ground sensors** |
|  |
| **Detail any challenges you faced and how you overcame them.** |